



# Racing Toward an Autonomous Future







Automated, Connected, Electric, Shared & Safe Mobility





#### ATI CENTERS



Alabama

**Transportation** 

Institute

#### **ALDOT COLLABORATION**





Alabama Mobility and Power Center

National Training Initiative for Electric Vehicle Technologies



Center for Advanced Public Safety

#### **UA COLLABORATING CENTERS**

Center for Advanced Vehicle Technologies

Institute for Data and Analytics



Center for Business and Economic Research Center for Insurance Information Research

#### **MULTI-INSTITUTIONAL CENTERS**



Center for Transportation Operations Planning and Safety

Center for Efficient Vehicles and Sustainable Transportation Systems

Rural Road Safety Center







Organized by Energy Systems Network, IAC university teams from around the world compete in a series of challenges to advance technology that can speed the commercialization of fully autonomous vehicles and deployments of advanced driver-assistance systems (ADAS) to increase safety and **performance.** The competitions are a platform for students to excel in Science, Technology, Engineering and Math (STEM).

#### Friday April 29, 2022 Daily Mail

### Robo-car breaks the world speed record! Fully autonomous PoliMOVE vehicle reaches an incredible 192.2mph on the Space Shuttle airstrip at NASA's Kennedy Space Center

- The car is a Dallara-built AV-21 that has hardware to enable automation
- It took to the track on the Space Shuttle airstrip in Cape Canavera on April 27
- The speed of 192.2mph was obtained as an average of over 0.6 miles (1km) in two consecutive attempts in opposite directions, to eliminate the effects of the wind

By SHIVALI BEST FOR MAILONLINE >

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A robotic car has broken the world speed record, reaching impressive speeds of 192.2mph (309.3kph).

The car, developed by a team from the Politecnico di Milano, called PoliMOVE, is fully autonomous and took to the track on the Space Shuttle airstrip at NASA's Kennedy Space Centre this week.

During the test drive, the racecar clocked speeds of 192.2mph (309.3kph), smashing the previous record of 175.49mph (282.42kph), held by Roborace.

## The Challenge

- Object is to deploy software to drive a standard issue racecar at high speeds under challenging performance conditions.
- Ocillaborating with partners like Cisco, the IAC is working to increase safety and performance in not only motorsports, but across all modes of commercial transportation.
- The IAC started as a \$1 million prize competition with 41 university teams signing up to compete more than two years ago, representing top engineering and technology programs from 14 U.S. states and 11 countries.
- UA is partnered with Politecnico di Milano (Italy) one of the top universities in the world.

## The Racecar

**Dallara AV-21 (modified Indy Lights chassis)** 

#### **Sensors on board:**

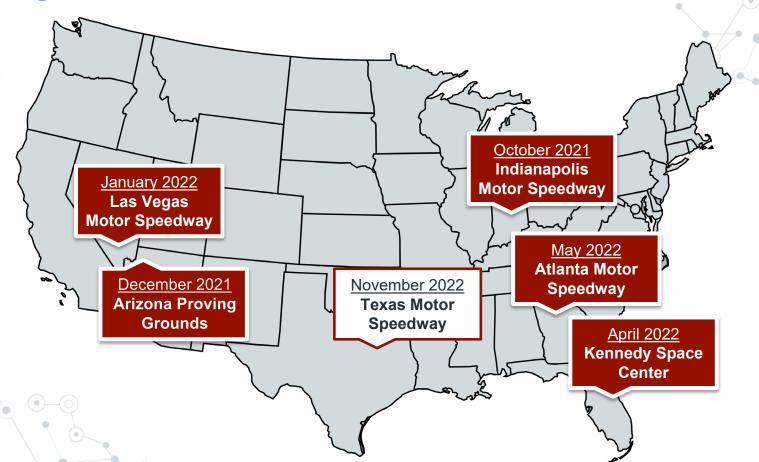
- ➤ High-Precision GPS
- > Radar
- Lidar
- Computer-Vision Cameras



## The PoliMOVE Team at the Indianapolis Motor Speedway Politecnico di Milano (Italy) and The University of Alabama



## Racing Across America...







## **EcoCAR Challenge Competitions**

- US Department of Energy competition
- 11 top universities
- Topics:

  - Advance propulsion systems

    Connected and automated technology
  - Improve energy, safety and consumer appeal
- Year 3
- Awards given June 9, 2021
- UA Won 1st Place
- We are one of the 13 teams chosen for Year 4



#### OVERALL AWARDS

1st Place Overall - University of Alabama

2nd Place Overall - Ohio State University

3rd Place Overall - West Virginia University

4th Place Overall - Mississippi State University



## Safety Implications

- Competition drives innovation
- The brightest minds and top innovators
- Vehicle dynamics Working in a controlled environment
- Build algorithms for edge cases
- Edge cases are important from safety perspective -
  - Don't come up often in the real world
  - But needed to control vehicle in emergency situations
- Technology developed will influence autonomous features in all vehicles, including CMVs

## **Thank You**

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